

# Configurable Field Magnets for a Proton Beam Dynamics R&D Ring

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## Abstract

Magnets with many independently-powered coils can provide nearly arbitrary combinations of multipoles up to a certain order. This paper gives examples of field quality in such an "omni-magnet", which is normal-conducting and simulated with Poisson. Since the magnets also have quite large apertures they may be used to make a general-purpose FFAG and synchrotron test ring for beam dynamics studies. This could use the 3MeV H<sup>-</sup> beam from the RAL proton Front End Test Stand (FETS) and outline ring parameters are given for that situation.

## Extending FETS with a Ring

- Electron models are not sufficient for simulating the beam dynamics of H<sup>-</sup> stripping injection, must use an ion species.
- The Front End Test Stand (FETS) at RAL is a source of H<sup>-</sup> ions at 3MeV, ~50mA current and 50Hz repetition rate.
- FETS already provides a high-quality beam with significant space charge and a fast/slow beam chopper integral to the design.
- Using configurable magnets would allow many synchrotron and FFAG lattices to be tested without having to build a model for each.

Table 1: Parameters of the Proton Omni-Ring

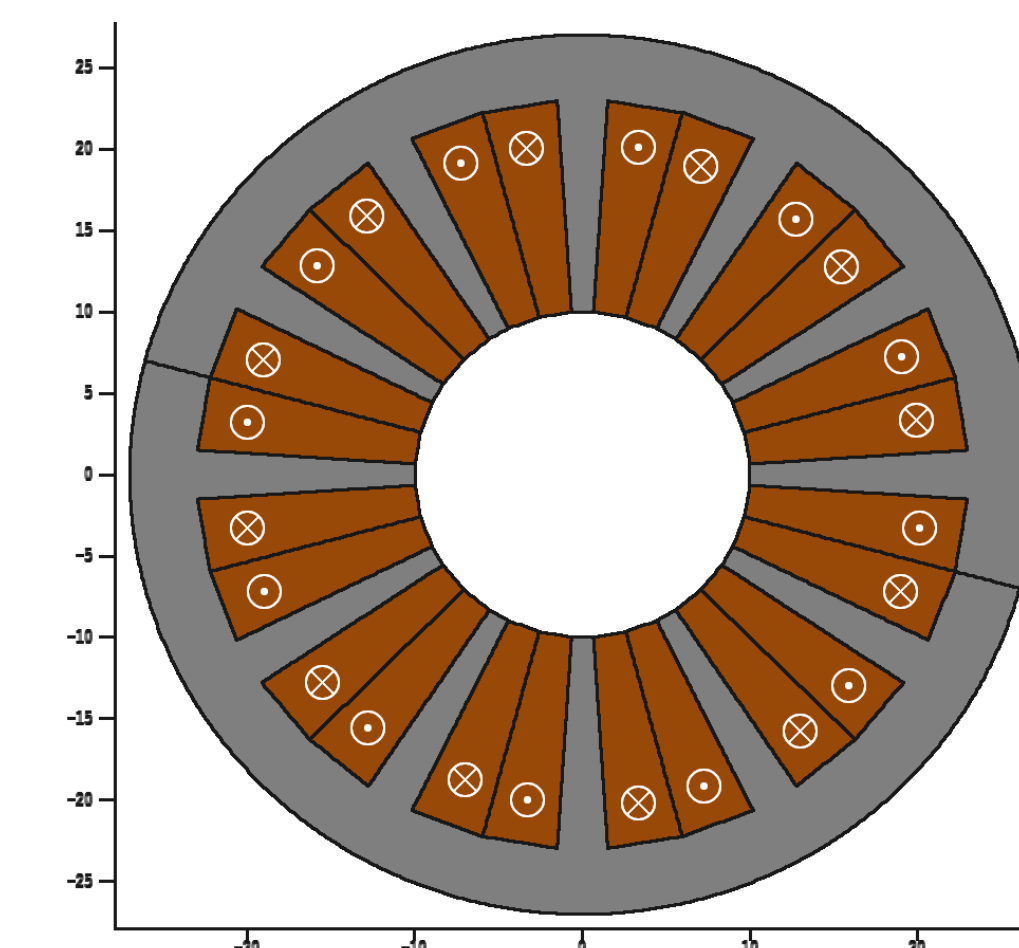
Beam energy	3	MeV
Beam momentum	75.09	MeV/c
Magnet packing factor	40	%
Mean dipole in magnet	0.2	T
Ring diameter	6.262	m
Revolution frequency	1.216	MHz

### Example cell structure

Magnets per ring	24
Cell length	0.8197 m
Magnet length	0.3279 m
Drift length	0.4918 m

- Injection line from FETS should ideally contain multi-axis kickers (and maybe an RF cavity) for injection painting, beam position and profile monitors, beam diluters to vary space charge and toroids.
- Fast extraction line from ring should contain diagnostics of the beam profile, halo and possibly emittance of any single turn.

## Omni-Magnet



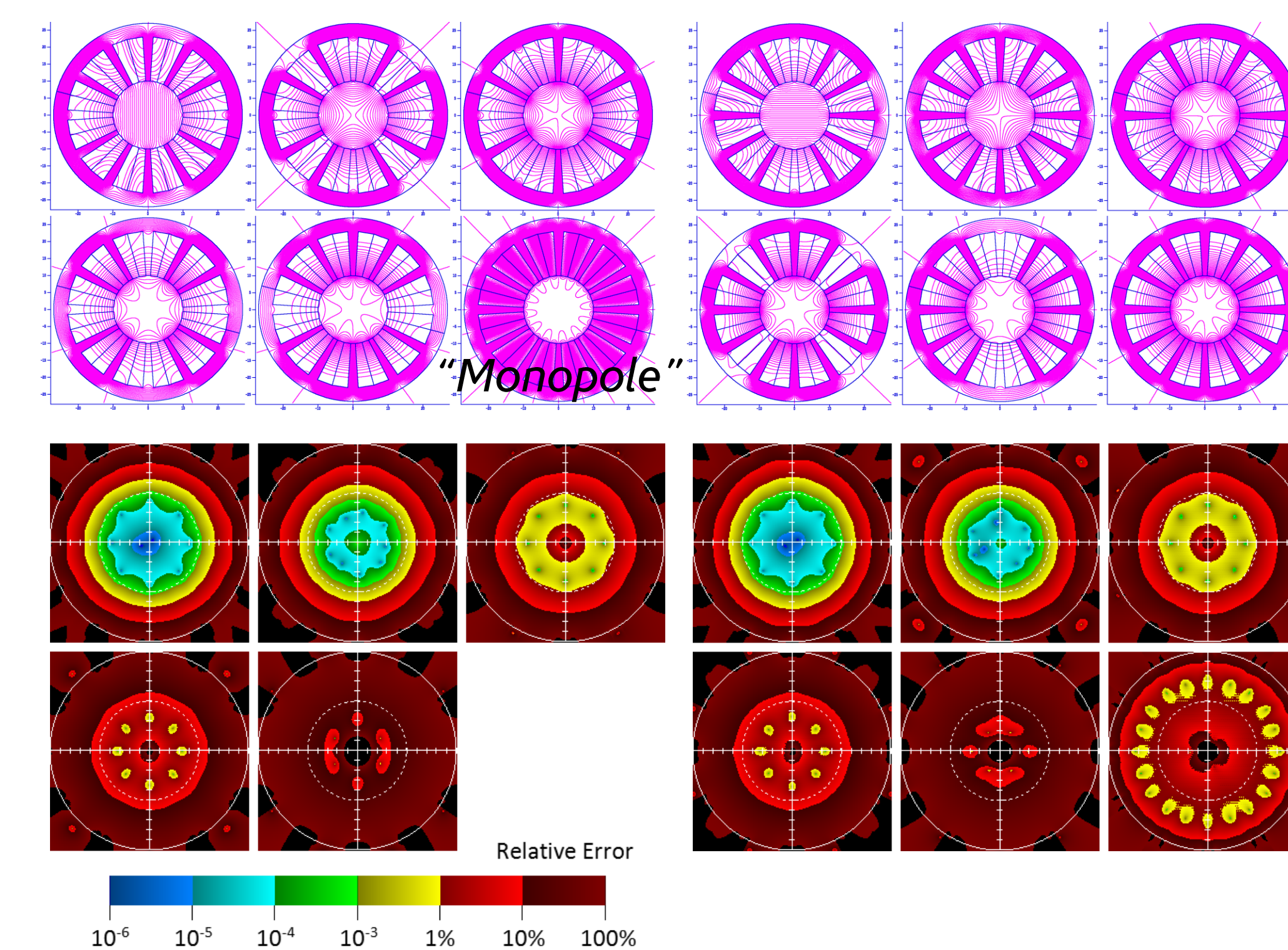
n	Pole	Max j A/mm <sup>2</sup>	Strength T/m <sup>n-1</sup>	Max B in poles Tesla
1	Dipole	5	0.241558	1.23
2	Quad	2.165	2.21262	1.13
3	Sext	1.667	39.36	1.37
4	Oct	1.083	1032	1.20
5	Deca	1	34800	1.30

n	Skew	Max j A/mm <sup>2</sup>	Strength	Max B in poles Tesla
1	Dipole	5	0.241558	1.23
2	Quad	2.5	2.21136	1.29
3	Sext	1.667	39.38	1.37
4	Oct	1.25	1032	1.38
5	Deca	1	34800	1.30
6	Dodeca	0.833	2892000	1.15

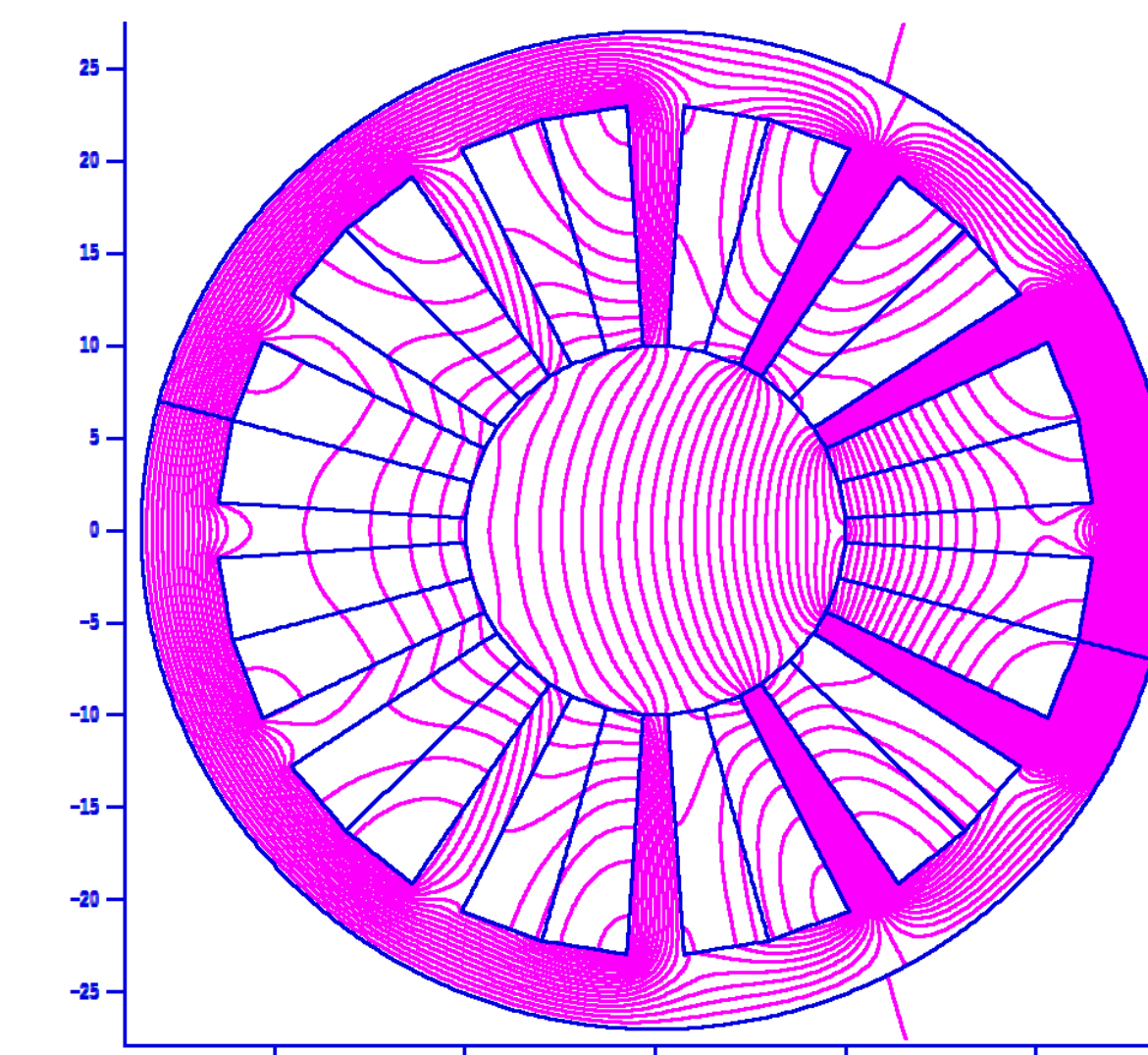
Above left: Cross-section of the omni-magnet. The magnet resembles a dodecapole but the current in each coil can be varied independently. The bore radius is 10cm, surrounded by 13cm-long poles and a 4cm-thick iron return yoke for a total radius of 27cm. The poles take up 25% of the angular fraction.

## Multipole Fields



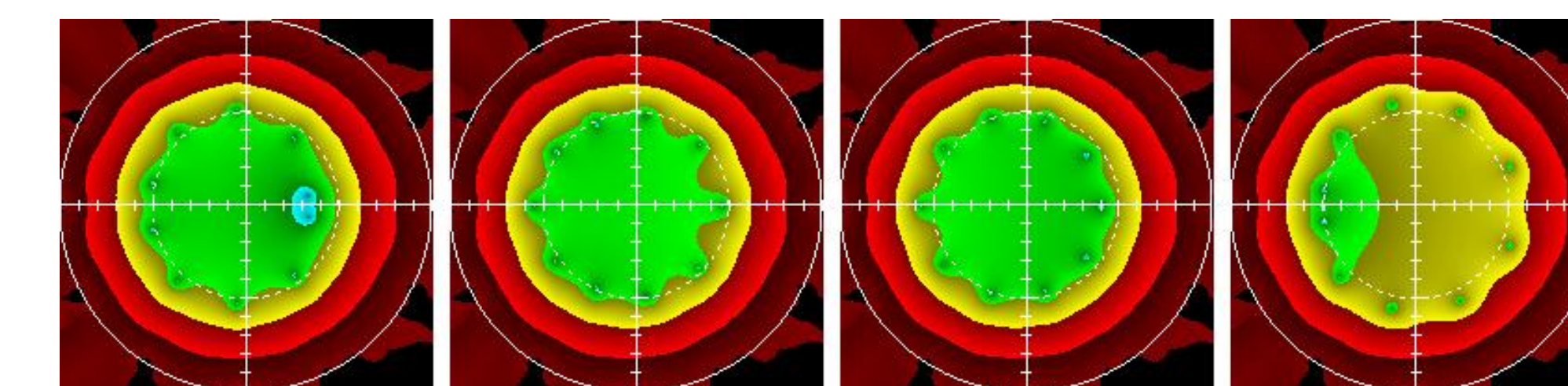
Above: (top) Fields generated by the omni-magnet in multipole (left) and skew multipole (right) current configurations. The current density in each winding is given by  $j = (5A/mm^2)\sin(n\theta)/n$ , with  $\sin$  replaced by  $\cos$  for skew poles. (bottom) Relative errors, defined by  $|B - B_{goal}|/|B_{goal}|$ , of the corresponding fields in the top row. Each plot shows x,y from -10 to 10cm, including the entire magnet bore. The same colour scale is used throughout this poster.

## Scaling FFAG Fields

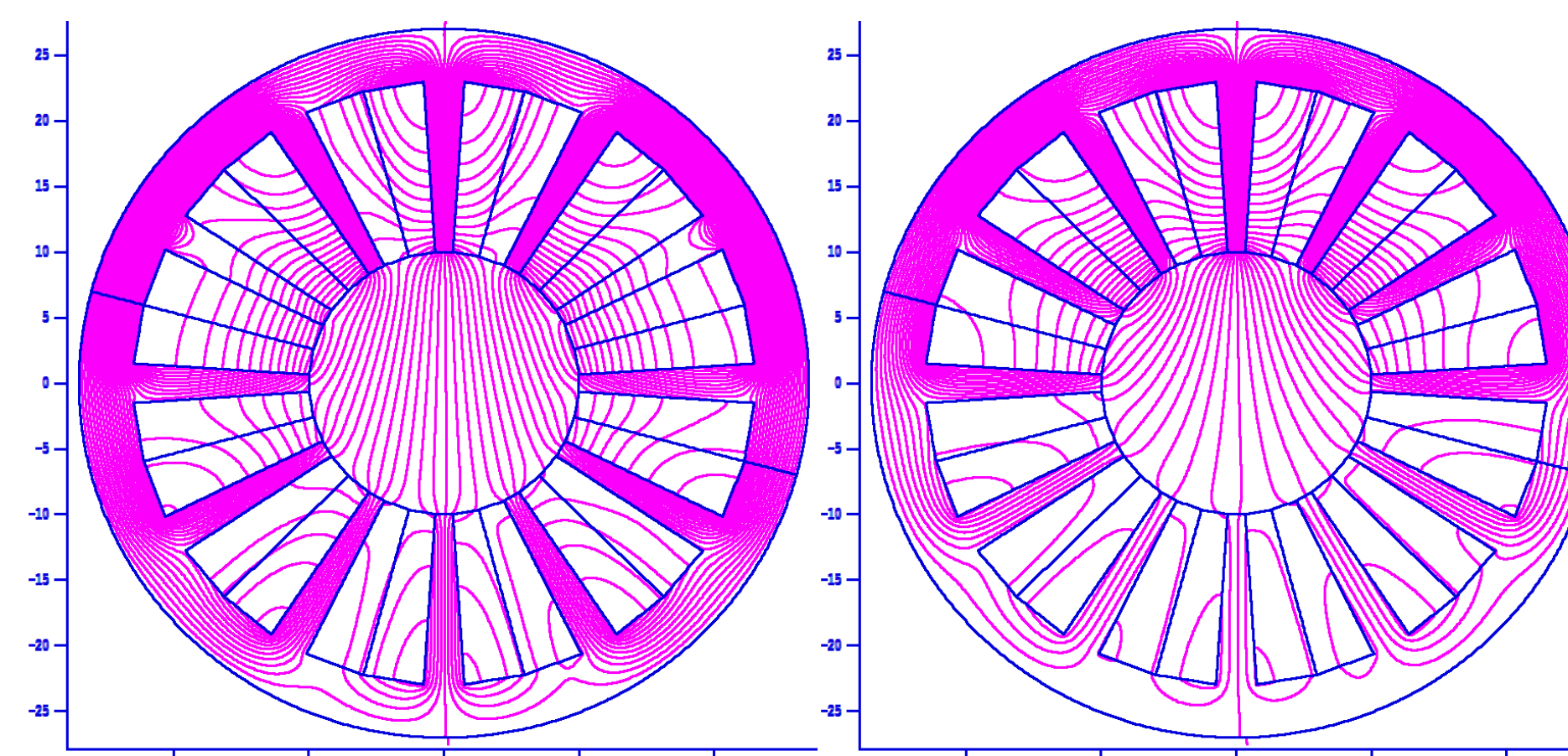


Left: Omni-magnet producing a scaling FFAG field by linearly combining multipole current configurations according to the Taylor series of the scaling FFAG field law:  $B_y = B_0(r/R_0)^k$  for  $y = 0$ , where  $r = R_0 + x$ . Here,  $B_0 = 0.2T$ ,  $k = 20$  and  $R_0 = 3.131m$ .

Below: Relative field errors in the  $k = 20$  scaling FFAG for field strengths  $B_0 = 0.05, 0.1, 0.15$  and  $0.2T$  (left to right).

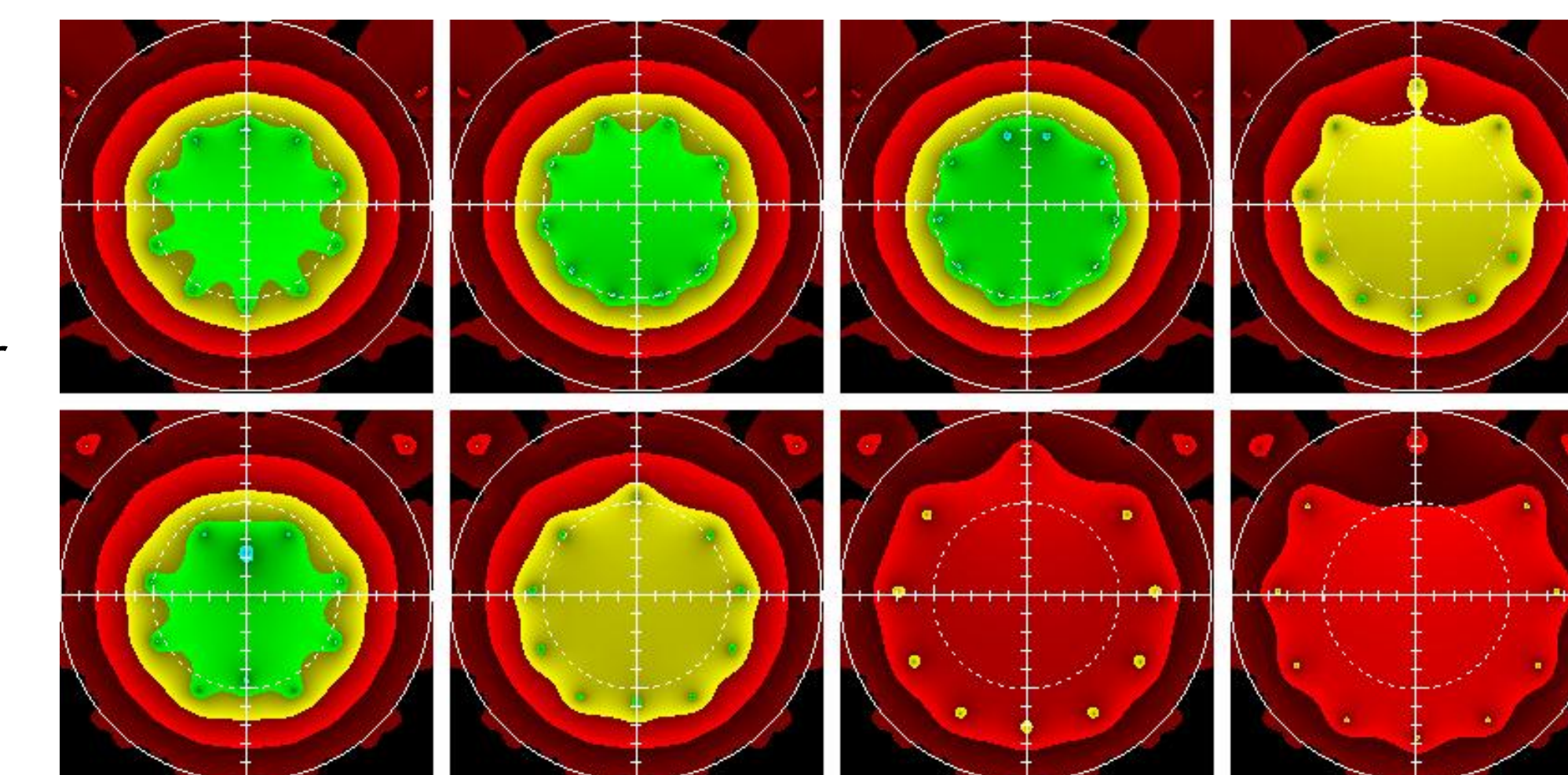


## Exponential VFFAG Fields



Above: Fields from the vertical orbit excursion FFAG scaling law ( $B_y = B_0 e^{ky}$  for  $x = 0$ ) for  $k = 5m^{-1}$  (left) and  $10m^{-1}$  (right).

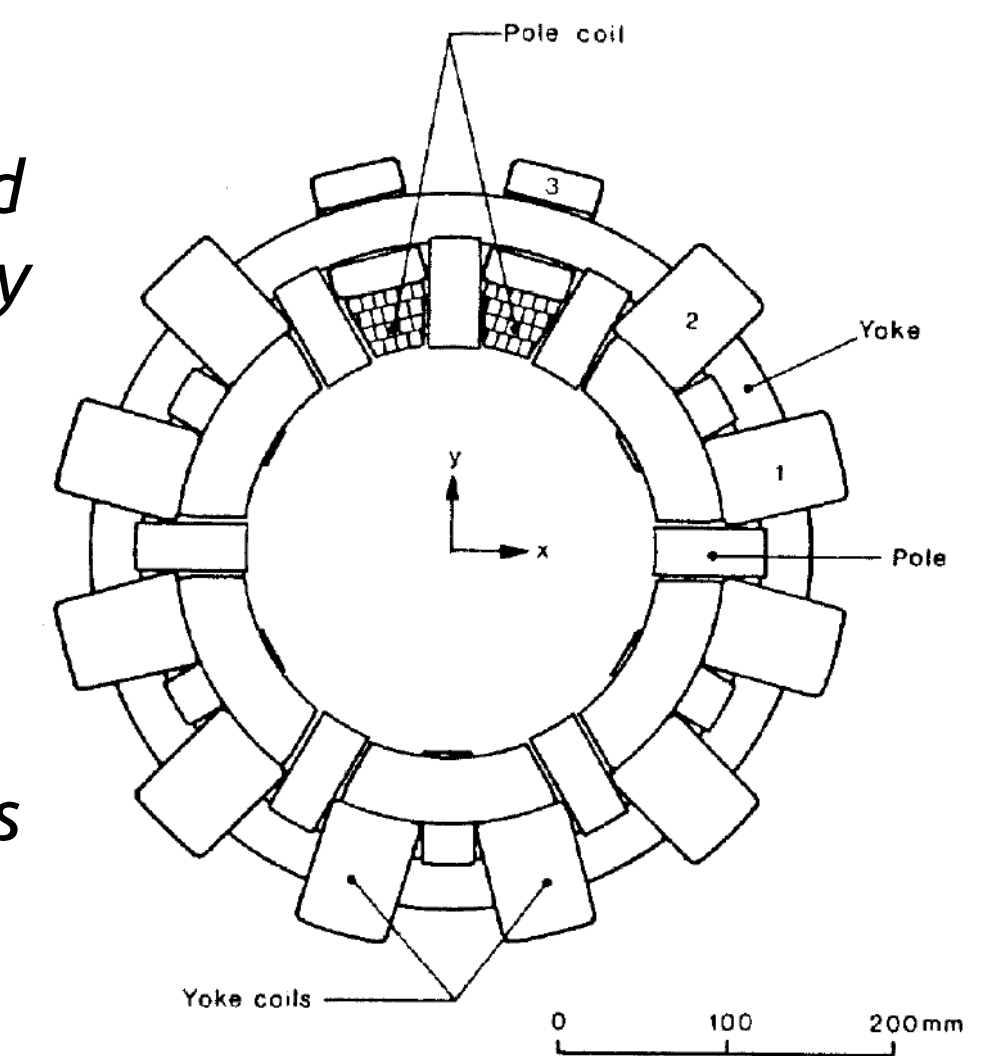
Below: Relative error plots for VFFAGs with  $k = 5m^{-1}$  (top row) and  $10m^{-1}$  (bottom row) for field strengths  $B_0 = 0.05, 0.1, 0.15$  and  $0.2T$  (left to right), saturation occurs towards bottom right.



## Field Strength Upgrades

The iron poles only take up 25% of the circumference of the magnet bore, so if the iron starts to saturate at 1.4T, the maximum field at the edge of the bore can only be 25% of this (0.35T) since all the flux lines have to bunch together to go through the iron. Higher field strength may be achieved in future by using thicker or non-tapering poles.

Right: The corrector magnets used in the SRS at Daresbury Laboratory (designed by Neil Marks) had a very similar principle to omni-magnets but operated at lower fields. They also have windings around the iron return yoke that may produce low-order multipoles using less current.

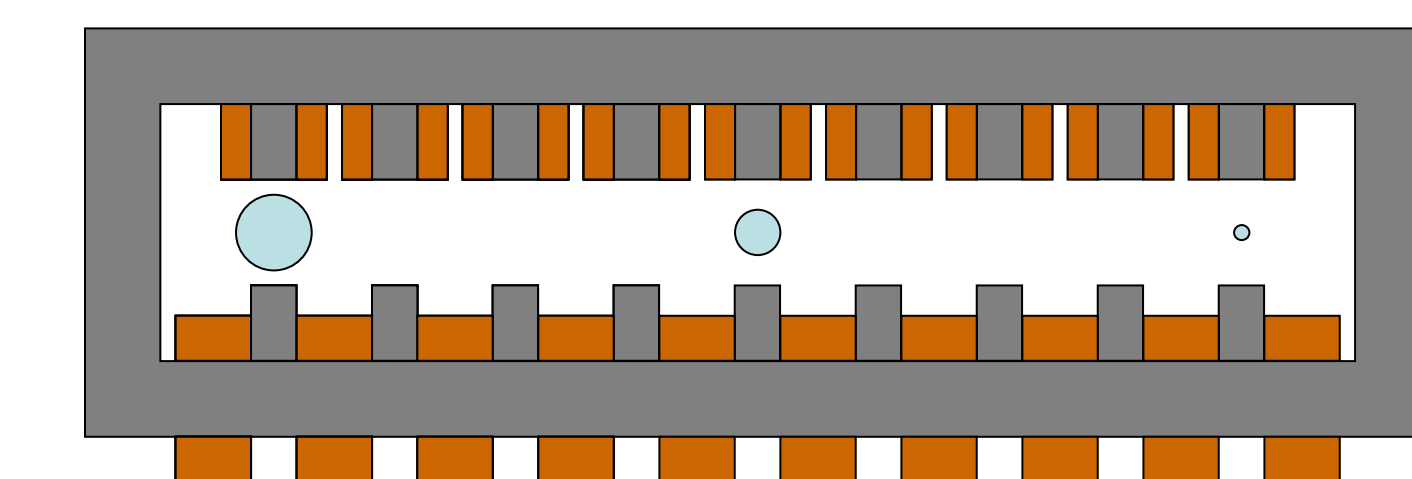


## Other Future Work

- Correction schemes have not yet been used to fine-tune the currents in these magnets; e.g. the higher-order poles have a small dipole defect that could be subtracted out. This will be necessary in the case of each real magnet as well as in the simulations.
- Fitting schemes such as least-squares error fitting of a polynomial can provide better field quality over a finite range than just using the Taylor series at a point.
- Operating with the iron in saturation can provide higher pole-tip fields at the expense of non-linear operation. It may be possible with very careful calibration.

## Slotted Variant for FFAG Correction

- A "hybrid FFAG" uses superconducting fixed-field magnets for main dipole and quadrupole, PLUS:
- "Omni-Corrector Magnet"



Alternative coil configuration shown on bottom half

- The above iron+copper magnet used for:
  - Static field/tune error correction in DC mode
  - In pulsed/programmable mode (~10kHz bandwidth):
    - Resonance jumping
    - Dynamic aperture improvement
    - [Optional] Resonant extraction